KU-Loiter MAV

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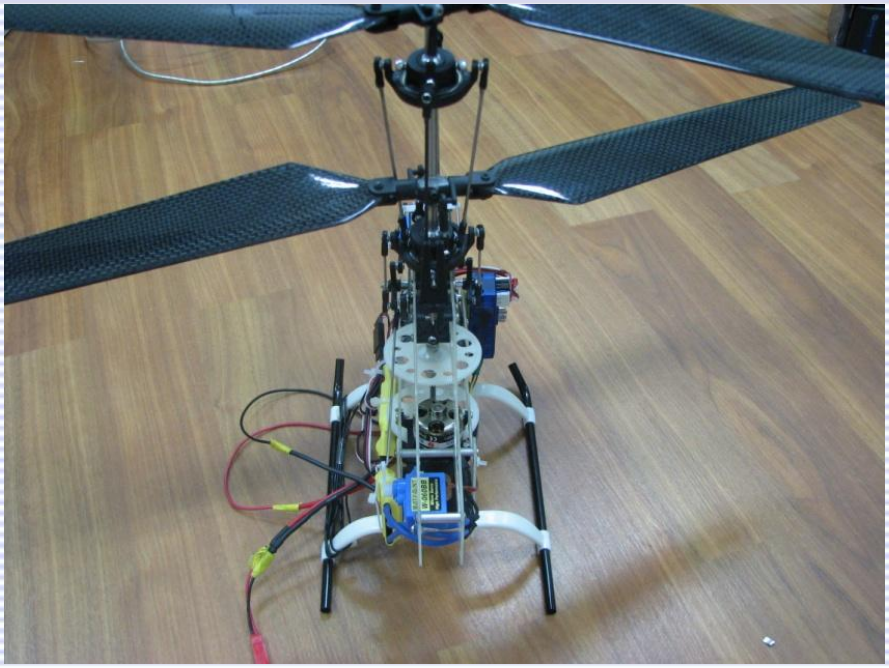
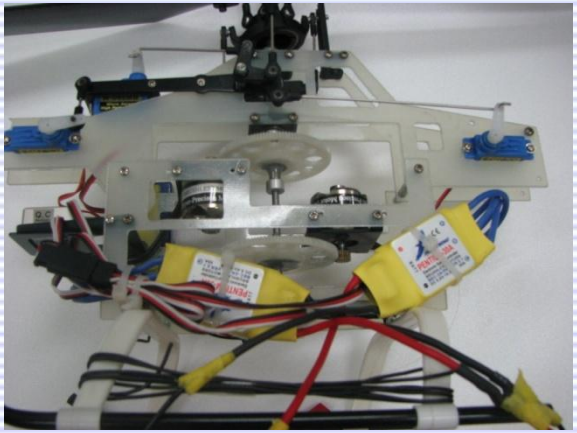
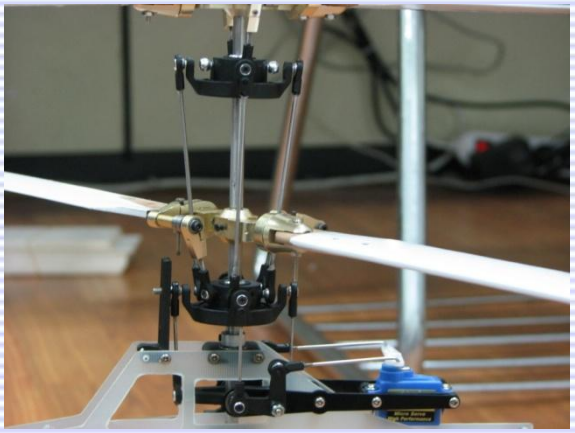
Model 1.

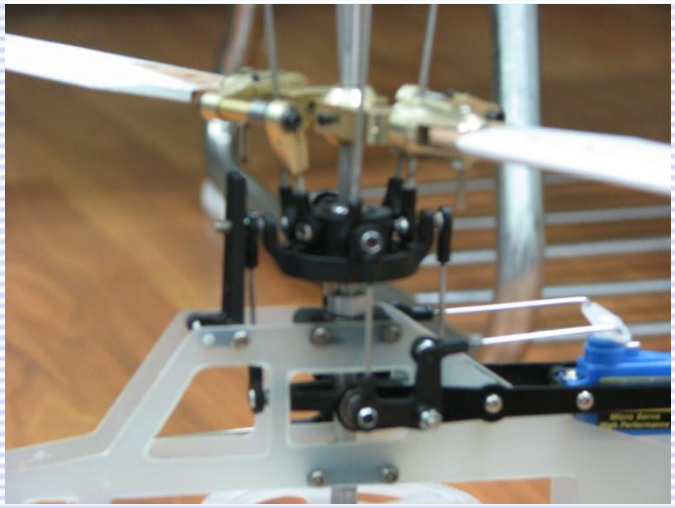


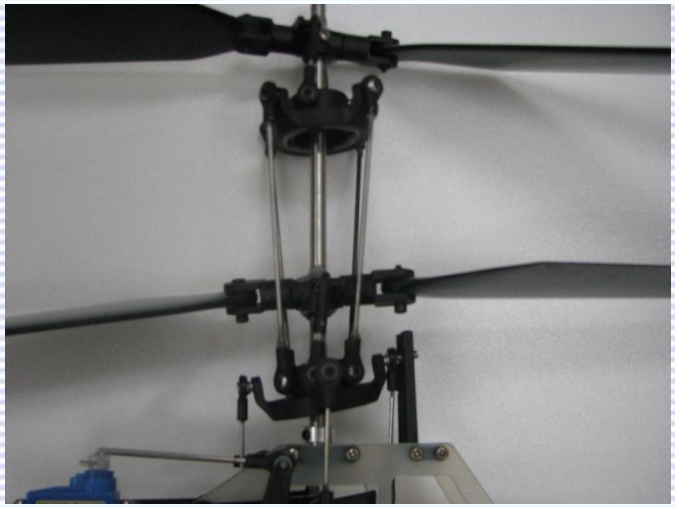
- For Outdoor mission purpose
- Co-axial rotary system
- Weight : 495g
- Rotor diameter : 49cm
- 2 swash plate – pitch control
- 2 motors, 3 servomotors, 7.4V-1800mA battery,
- 1 CMOS camera





Model 1.





1. **Changed head of rotor from steel to plastic due to its over weight**
2. **Yaw control by controlling RPM of 2 motors**
3. **Current Situation**
   - **Difficulties occurred by mixing 2 motors in 1 gyro system**
   - **Overweight due to adapting Auto-pilot system**

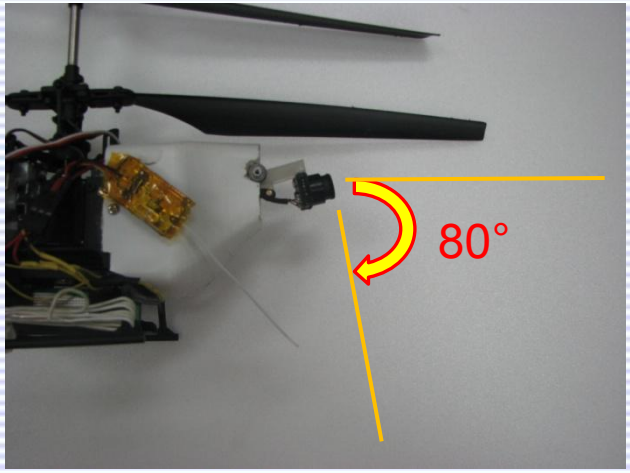
→ **Decided to participate in indoor mission instead of outdoor with smaller rotary wing MAV**

Model 2.

- **Modified COTS**
- **Co-axial rotary system**
- **Weight : 241.5g**
- **Rotor diameter : 36cm**
- **1 swash plate**
- **2 motors, 2 servomotors, 7.4V-800mA battery,**
- **1 CMOS camera**

Model 2.

- Vision sensor included



Model 2.

- Flight movie

- Vision image from camera

Thank you …